

BAKER COLLEGE STUDENT LEARNING OUTCOMES

ME 4870 Mechatronics 3 Semester Hours

Student Learning Outcomes & Enabling Objectives

- 1. Explain mechatronic systems and their applications
 - a. Describe the components of a mechatronic system
 - b. Describe examples of real-world mechatronic systems
- 2. Explain microcontrollers
 - a. Distinguish microprocessors and microcontrollers
 - b. Describe the components of a microcontroller
 - c. Program a microcontroller to perform basic functions
- 3. Examine data acquisition and microcontroller interfacing
 - a. Explain characteristics of analog/digital and digital/analog converters
 - b. Describe various interfaces: parallel, serial, SPI, I2C, USB
- 4. Examine sensors, their performance and uses in mechatronic systems
 - a. Explain the operation of different types of sensors
 - i. displacement
 - ii. proximity
 - iii. speed
 - iv. temperature
 - v. vibration
 - vi. other sensors
 - b. Interpret sensor performance specifications
 - c. Select appropriate sensors for specific applications
- 5. Examine actuators, their performance and uses in mechatronic systems
 - a. Explain the operation of DC, AC, stepper and servo motors
 - b. Interpret the torque-speed characteristics of an actuator
 - c. Select an appropriate actuator for a specific application
- 6. Apply mechatronics concepts in experimental settings
 - a. Test components of mechatronic systems, sensors and actuators, and program microcontrollers
 - b. Complete a project involving a mechatronic system with the above components